

## DC-Servomotor KN 16 M4 inch version

### Characteristics

Rated Values <sup>1</sup>			
Nominal torque	$M_N$	320	Ncm
Nominal speed <sup>2</sup>	$n_N$	3000	min <sup>-1</sup>
Nominal output <sup>2</sup>	$P_N$	1000	W
Terminal voltage	$U_N$	128	V
Nominal current	$I_N$	9,3	A

Motor Performance			
Peak torque <sup>3</sup>	$M_{max}$	3500	Ncm
Max. peak current <sup>3</sup>	$I_{max}$	100	A
Acceleration at peak torque	$a_{max}$	63	10 <sup>3</sup> rad/s <sup>2</sup>
Stall torque <sup>4</sup>	$M_0$	325	Ncm
Current at stall torque <sup>4</sup>	$I_0$	8,8	A
Max. load speed	$n_{max}$	4000	min <sup>-1</sup>
Max. no load speed	$n_0$	6000	min <sup>-1</sup>

Intrinsic Motor Constants			
Torque constant	$k_T$	38,4	Ncm/A
Back E.M.F constant	$k_E$	40,2	V/10 <sup>3</sup> min <sup>-1</sup>
Viscous damping constant	$k_D$	6,5	Ncm/10 <sup>3</sup> min <sup>-1</sup>
Speed regulation at const. Voltage	$k_n$	0,65	min <sup>-1</sup> /Ncm
Average Friction Torque	$M_F$	6,9	Ncm
Terminal resistance (+25 °C)	$R_A$	0,94	?
Armature (Cu) resistance (+25 °C)	$R_{Cu}$	0,74	?
Armature Inductance (10 <sup>3</sup> Hz)	$L_A$	<0,06	mH
Mechanical time constant	$T_m$	3,9	ms
Electrical time constant	$T_e$	<0,08	ms
Rotor inertia	$J$	5,95	kg cm <sup>2</sup>

Thermal Characteristics			
Time const. armature-housing	$T_{th1}$	1,82	min
Time const. housing-ambient	$T_{th2}$	32,8	min
Resistance armature-housing	$R_{th1}$	0,83	K/W
Resistance housing-ambient	$R_{th2}$	0,59	K/W
Temp. - coeff. of back EMF	$c_{th}$	-0,08	%/K
Max. cont. armature temp.	$th$	155	°C

Physical Data			
Number of magnet poles	2p	8	pcs
Number of commutator bars	z	162	pcs
Admitted shaft load, radial	$F_R$	380	N
Admitted shaft load, axial	$F_A$	375	N
Weight without extensions	$m$	6,0	kg

<sup>1)</sup> for DC current with formfactor 1,05, uncooled execution, protection IP 54, ambient temperature +40 °C.

<sup>2)</sup> Continuous operation S1 (VDE 530), part 1,4. Motor can be run at all points of the torque speed curve S1, continuous speed beyond 4000 min<sup>-1</sup> is not recommended, please check the torque speed curve.

<sup>3)</sup> Incremental motion cycle S3, VDE 530, part 1,4. Pulse duration 50 ms, 1% of duty cycle.

<sup>4)</sup> Point of intersection torque speed curve S1 with torque co-ordinate at speed zero. Permitted at very low speed < 1min<sup>-1</sup>. Works the motor with blocked shaft longer than 20 s, the stall current must be reduced to approx. 70%.

<sup>5)</sup> Based upon mounted motors, heat transfer from motor to equipment.

Outline dimensions motor:

grey diagrammed hood optional

